# Exponential Time Differencing Methods for Numerical Self-Consistent Field Theory

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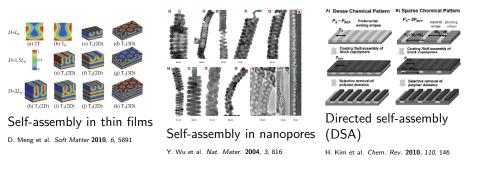
### Outline

- Introduction
- Numerical Methods
- Performance of ETDRK4 Methods
- Applications of ETDRK4 Methods
- Summary
- Acknowledgments

### Introduction

Self-Assembly of Block Copolymers under Confinements

#### In practice, most of block copolymers are more or less under confinement.



Surface and interfacial effects play an important role in determining the self-assemble structures.

### Introduction

Modeling Surface and Interfacial Effects in Self-Consistent Field Theory (SCFT)

#### Approach I:

Using a masking technique and introducing surface interaction terms.

#### Approach II:

Imposing Robin boundary conditions on the modified diffusion equations for propagators.

$$\frac{\partial q}{\partial n} + \kappa q = 0$$
 at the boundary

### Introduction

SCFT Methods for Confined Block Copolymers

### Operator splitting with Fourier collocation (OSF, OSS, OSC).

- Fast,  $O(M \log M)$ .
- Often 2nd order convergence in temporal domain.
- Accuracy degradation for Dirichlet and Neumann boundary conditions (DBC and NBC).
- Not applicable for Robin boundary conditions (RBC).

### Operator splitting with Cheyshev collocation (OSCHEB).

- $O(M \log M + \alpha M)$  with large coefficients  $\alpha$ .
- Often 2nd order convergence in temporal domain.
- Can handle RBC but requires even larger coefficients.

### Other real space methods (finite difference), spectral methods.

### Numerical Methods

Exponential Time Differencing Scheme

Modified diffusion equation in matrix form

$$\frac{\partial q}{\partial s} = \mathbf{L}q + \mathbf{F}(q, s)$$

In exponential form

$$rac{\partial}{\partial s}e^{-\mathsf{L}s}q=e^{-\mathsf{L}s}\mathsf{F}(q,s)$$

Stepping a single contour step

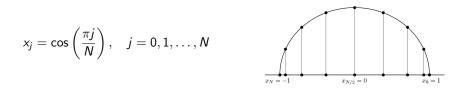
$$q(s_{n+1}) = e^{\mathsf{L}s}q(s_n) + e^{\mathsf{L}s}\int_0^h d\tau \mathsf{F}\left[q(s_n+\tau), s_n+\tau\right]$$

Then a 4th order Runge-Kutta method is employed to approximate the integral.

### Numerical Methods

Chebyshev Collocation and Boundary Conditions

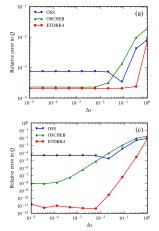
To efficiently handle non-periodic boundary conditions, we discretize spatial variables on a Chebyshev-Gauss-Lobatto grid with a set of points



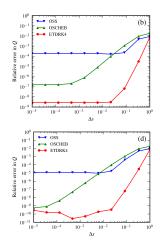
- L can be constructed from the Chebyshev differentiation matrix D.
- Boundary conditions are imposed by incorporating appropriate terms in L.

Convergence in Temporal Domain

ETDRK4 exhibits 4th order accuracy in temporal domain.



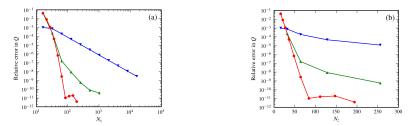
(a) N = 32, (b) N = 64, (c) N = 128, (d) N = 256



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Convergence in Spatial Domain

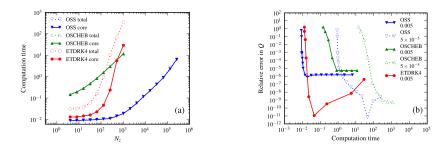
ETDRK4 retains spectral convergence in spatial domain.



(a) log-log plot, (b) semilog plot. Disk: ETDRK4, up triangle: OSCHEB, down triangle: OSS.

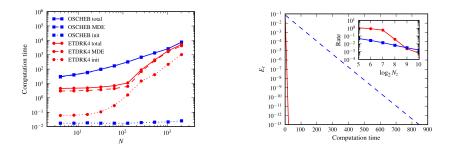
**Computational Cost** 

For high accuracy calculations (error  $< 10^{-6}$ ), ETDRK4 is more efficient than OSS and OSCHEB.



Full SCFT Calculations

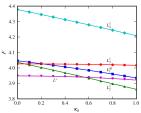
#### With ETDRK4, the SCFT algorithm also converge exponentially.



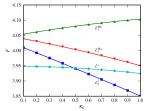
# Applications of ETDRK4

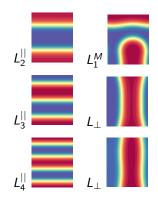
Free Energy Calculations

AB diblock copolymer confined by two parallel flat surfaces.



Symmetric surface interactions



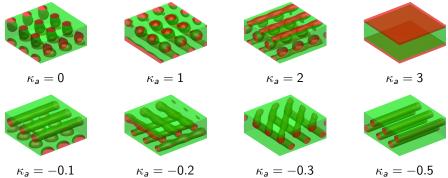


#### Asymmetric surface interactions

# Applications of ETDRK4

3D calculations

AB diblock copolymers confined by two parallel flat surfaces.



### ETDRK4 methods

- Fast for high accuracy calculations.
- 4th order accuracy in temporal domain.
- Spectral accuracy in spatial domain.
- Applicable to RBC without significant increase of computational cost.

#### Limitations

• Computational cost increases rapidly for non-periodic boundary conditions in two or more dimensions.

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# **Thanks!**